

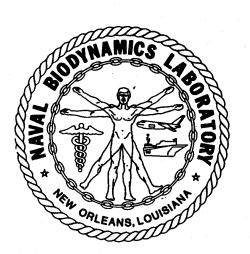
X-RAY ANTHROPOMETRY TRANSFORMATION PROGRAM FOR THE HEWLETT-PACKARD 9000/835 COMPUTER

DOROTHY FRANCIS

Software Documentation

May 1991

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X-RAY ANTHROPOMETRY TRANSFORMATION PROGRAM

FOR THE HEWLETT-PACKARD 9000/550 COMPUTER

1. INTRODUCTION

The Naval Biodynamics Laboratory (NAVBIODYNLAB), located in New Orleans, Louisiana, is a research facility under the cognizance of the Naval Medical Research and Development Command. It is the only Navy laboratory conducting biomedical research on the effects of mechanical forces (motion and impact) encountered by Navy personnel. Among its goals are the establishment of human tolerance limits and the development of appropriate methods of avoiding and treating the deleterious effects of such forces. Ongoing research programs at the laboratory acquire sensor and photographic impact acceleration data from acceleration sled runs.

To analyze this data, certain anthropometric information about each subject is necessary: the locations of the head and the first thoracic vertebral body (T-1) instrumentation origins relative to the corresponding anatomical origins, as well as transformation matrices from the instrument to the anatomical coordinate systems.

A stereoradiographic technique, in which two simultaneous X-ray exposures of an instrumented subject are prepared and analyzed, is used to measure the geometrical relationships between subject mounted-instrumentation and subject anatomy. This yields a complete six-parameter statement of the position and orientation of the instrument package relative to a coordinate system fixed in the subject's bony anatomy. In the anatomical coordinate system, the mounted instrumentation is assumed to be rigidly fixed. If the geometrical relationship of these systems is known, then the transformation from one system to the other is a matter of rigid body mechanics.

Stereoradiographic techniques have been devised at the Naval Biodynamics Laboratory to measure the geometrical relationships between subject-mounted instrumentation and subject anatomy. Measurements for instrumentation mounts are made at the head and T-1.

Packages consisting of photographic targets and accelerometers that are fixed to a rigid T-shaped plate are attached to human and human analog subjects by means of an intermediary anatomical mount. These mounts are prepared so that one surface provides a rigid and highly repeatable mooring for the instrumentation packages, while another is custom molded to fit the subject's dental surfaces or bony protuberances of the spine or pelvis. The transformation from anatomical to instrumentation coordinates is governed by these anatomical mounts, with a single transformation uniquely associated with each.

Quantization of these transformations is performed radiographically. The subject is X-rayed while wearing lead markers on externally accessible anatomical features. Also worn are anatomical mounts equipped with special PlexiglassTM T-plates, in which additional lead markers ("BBs") have been fixed at known locations. The X-ray images of these markers and of other anatomical features establish the laboratory reference position of the test subject and the orientation of the instrumentation and anatomical coordinate systems. This information is used to convert anatomical to instrumentation data.

Two groups of anatomical coordinates are presently used in the work conducted at NAVBIODYNLAB. One is located in the bony anatomy of the head, the other in the first thoracic vertebral body (T-1). The head coordinate system is defined by the positions of the two auditory meatus and the notches on the inferior orbital ridges. Its origin is the midpoint of the line joining the auditory meatus. The X axis is positive from the origin through the midpoint of the line connecting the orbital notches. The X-Y plane contains the X axis and the midpoints of the lines from the left orbital notch to the left auditory meatus and from the right orbital notch to the right auditory meatus. The Z axis is positive through the top of the skull. The T-1 coordinate system is also based on four points: the posterior tip of the posterior spinous process, the anterior-superior corner of the vertebral body, and the superior corners of the right and left articular facets. Unfortunately, most of these points are not directly accessible for marking and are visible only in certain X-ray projections.

Therefore, the suprasternal notch, an externally accessible site, is used to locate a system with the anterior-superior corner at T-1, with the X axis going through the posterior tip of the posterior spinous process and positive anteriorly, and with the Y axis parallel to the line connecting the two articular facets and positive left. The Z axis is positive up.

Since the radiologic equipment used at NAVBIODYNLAB is primarily intended for diagnostic use rather than for stereometric measurement, there is no direct means of obtaining a precise statement of the system geometry necessary for this application. Therefore, stereoradiographs of a special calibration device are prepared. This device consists of thirteen lead markers set at known positions in a radiolucent PlexiglasTM prism. The prism is placed so that at least eight of the markers will be visible in each of the two X-ray exposures. The body coordinates of this prism as it is radiographed become the arbitrary laboratory reference frame. Two X-rays are taken, an anterior-posterior and a lateral projection. Markers placed on the auditory meatus and the notches of the inferior orbital ridges, as well as those in the PlexiglasTM T-plate, are clearly visible in them. The positions of these images in each of the projections can then be made to yield their lab-oriented positions, which will in turn yield the orientations and lab-oriented positions of the anatomical and instrumentation coordinates, and finally the transformation from one to the other.

The anterior-posterior and lateral X-rays are also used to quantize the T-1 instrumentation coordinate data. Markers placed on the suprasternal notch and over the T-1 posterior spinous process, as well as those in the plexiglass T-plate, are clearly visible in each X-ray. In addition, the superior corners of the right and left articular facets are visible in the anterior-posterior X-rays, and the anterior-superior corner and the superior and inferior corners of the posterior spinous process are visible in the lateral ones.

After X-rays have been taken and developed, they are examined to determine that all the various markers and anatomical features are visible. The person overseeing radiological operations locates and marks the various anatomical landmarks for digitization. In digitization, the position of each marker and landmark is measured and compared to the orientation information. Digitized positions are subjected to computational procedures to determine, first, the geometrical layout of the radiologic equipment, and then the geometry relating the mounts to the anatomy. The computation is essentially a least squares iteration.

2. FUNCTION

The following program and subroutines are used:

MXRAY: Main program, which allows operator to select major

options.

AXEB: Inverts a matrix.

CDNTPT: Calculates and prints transformation matrices.

POBKG: Calculates the likeliest position and orientation of a

rigid body of known geometry.

PXRY2: Calculates the least-squared coordinates.

RLSWCH: Right-left switch.

OPTION: Compares calculations and uses switched values if

indicated.

PRISM2: Reads and reduces calibration data.

HTRANS: Calculates the position and orientation of the head

coordinates.

3. MAIN PROGRAM

3.1 MXRAY

This interactive program calculates X-ray anthropometry transformation matrices. The output consists of a printout and a data file containing the "Instrumentation vs. Anatomy" matrix, which is the input to the Anthropometry Data Base Update program. The following input is requested:

Subject Number (A6 format)

Date of X-ray (MON YR A6 format)

Julian Date of X-ray (I5 format)

Pcode (a for A-plate or t for T-plate, A1 format)

Julian Date of X-ray (day, year; I3,I2 format)

Option code "jo" and processing code "kk" (2I1 format)

jo = 1 exercise the option (standard

operation — always 1)

jo = (any other number) option not exercised

kk = 1 process head and neck data

kk = 2 process head data only

kk = 3 process neck data only

kk = 4 process pelvic data only

kk = 7 redo program

kk = 9 end program

Comments for head data

Comments for neck data Block or No block for neck data

3.2 COMPILATION

All of the subroutines needed to execute MXRAY are stored in the file 'libxrayantm.a,' which is in the users' library ('/usr/lib/'). The program was compiled with the following command:

fc mxray.f /usr/libxrayantm.a -o mxray

3.3 DATA FILES

The file 'input' should always contain the subject data to be processed. The file 'output' will always be used to store the processed data. The file 'update' will always be used to store the transformation matrices. The file 'IOupdate' is a shell procedure that updates the input file, saves the previous output, and executes the main program.

3.4 EXECUTION

The executable code is stored in the file 'mxray.' To execute the program, execute the shell procedure 'IOupdate' by typing the appropriate file names in the following form:

${\it IO} update\ new input filename\ old output filename\ old update filename$

Assuming subject H00290 was processed, the output from program execution is in files 'output' and 'update.' The data will be saved on the next execution of 'IOupdate.' The user input would be as follows:

IOupdate input H00290.out H00290.up

The file 'input' contains data for the subject to be processed. The naming convention for the files 'oldoutputfilename' and 'oldupdatefilename' is 'subjectID.out' and 'subjectID.up,' respectively.

The program will request input, organize and coordinate calculations. To get printed results, execute the "lp" command using the file 'output.'

4. SUBROUTINE DESCRIPTIONS

4.1 AXEB

The routine AXEB inverts a matrix. The call is:

call axeb (a,n,n1,jc)

where

A = the matrix to be inverted

N = the number of rows in matrix A

N1 = the number of columns in matrix A

JC = the work array used by this routine

4.2 CDNTPT

The routine CDNTPT calculates in anatomical coordinates the vector from the instrument origin to the anatomical origin. It also generates the transformation matrix that translates a vector from the instrumentation coordinate system to the anatomical coordinate system. The call is:

call cdntpt

4.3 POBKG

The routine POBKG calculates the vector defining the instrument origin lab coordinates and also calculates the transformation matrix from the instrument to the laboratory system. The call is:

$call\ pobkg\ (x,xx,ii,pp,a)$

where

- X = represents a two-dimensional, three-by-three array containing the best least squares coordinates of the center right, and left T-plate BBs in the lab coordinate system as calculated in subroutine PXRY2
- XX = a two-dimensional, three-by-three array containing the location of the three instrument BBs in the instrument coordinate system
- II = the number of BBs on the T-plate (normally 3)
- PP = the vector defining the instrument origin in lab coordinates

A = the transformation matrix (3 x 3) that takes a vector from the instrument coordinate system and translates it into the lab coordinate system

4.4 PXRY2

The routine PXRY2 calculates the best least square coordinates in the lab coordinate system. The call is:

$call\ pxry2\ (x,a,r,xr)$

where

X = the best least squares estimate of BBs in lab coordinates

A = the measured X-ray coordinates of the nth BB

R = the sum of the square of the error between the measured and the projected X-ray coordinates

XR = the X-ray coordinates obtained by projection of the calculated position of the BB onto the X-ray film planes

4.5 RLSWCH

The routine RLSWCH allows an optional right-left switch of the anterior-posterior (AP) and lateral X-ray coordinates. The call is:

call rlswch (j,k,sp)

where

J = represents the index of the right side BB on the lateral view as obtained from measurement

K = the index of the right side BB so labeled by this subroutine and has identical X-ray coordinates as the measured labeled left side BB

SP = the array containing the measured coordinates of the AP and lateral views. This array also contains the right-left/left right switch of coordinates in the last 24 elements

4.6 OPTION

The routine OPTION compares the error associated with the measured location of right and left BBs with the error associated with the right and left BBs as defined in subroutine RLSWCH. If the error is smaller for the point as labeled, the routine prints "Option Not Indicated." If the error is greater, the routine may either disregard the as-labeled calculation and use that of the switched labels (defined by subroutine RLSWCH) and print "Option Indicated and Exercised"; or, if the operator wishes, continue to use the as-labeled calculation and print "Option Indicated But Ignored." The call is:

call option (j,k,er,x,jo)

where

J = the number of the right-side BBs as obtained from lateral view measurements

K = the number of the right-side BBs as labeled by subroutine RLSWCH

ER = a one-dimensional array containing the sum of the squares of the difference between the "measured" and "calculated" AP and lateral X-ray coordinates of the BB under scrunity

X = two-dimensional, three-by-thirteen array containing the best least squares coordinates for the BB under scrutiny, as calculated in subroutine PXRY2

JO = the code that determines if an option is to be exercised, as follows:

1 — Exercise option

Any other number — Do no exercise option

4.7 PRISM2

The routine PRISM2 reads and reduces calibration data. This subroutine establishes the lab coordinate system and calculates both the AP and lateral camera orientations and positions. The call is:

call prism2 (xop,xsp,cp)

where

XOP = the best estimate of the vector from lab to X-ray origin in X-ray coordinates

XSP = the best estimate of the vector from source origin to X-ray origin in X-ray coordinates

CP = the best estimate of the transformation matrix
 from lab to X-ray

4.8 HTRANS

The routine HTRANS calculates the anatomical origin of the head in lab coordinates and the transformation matrix, which takes a vector in lab coordinates and transforms it into a vector in the head anatomical coordinate system. The call is:

call htrans (x)

where

X = the array containing the lab coordinates of the four head anatomical BBs plus the three T-plate BBs plus the six coordinates obtained by performing a right-left/left-right switch of measure-defined locations of BBs from the X-ray view

5. UTILITY SUBROUTINES

Two utility subroutines are used in the X-ray transformation program and are included for completeness. A brief description of each is given in this section.

5.1 CAPS

The routine CAPS enables the 'caps' mode on the HP-2627A terminal. The call is:

call caps

5.2 CAPOFF

The routine CAPOFF disables the 'caps' mode on the HP-2627A terminal. The call is:

call capoff

REFERENCE

Becker, E. B., "Stereoradiographic Measurements for Anatomically Mounted Instruments," Proceedings of the Twenty-First STAPP Car Crash Conference, Society of Automotive Engineers, Inc., Warrendale, PA, pp. 477–505, October 1977.

APPENDIX A

Program Listings

FORTRAN 77/UX HP92430A.07.04 COPYRIGHT HEWLETT-PACKARD CO. 1983. Thu Jul 26 14:20:18 1990

```
subroutine axeb (a,n,n1,jc)
 2
3
    C
       This routine inverts a matrix
    C
 4
    C
 5
    С
       а
              matrix to be inverted
              number of rows in matrix a
 6
    С
       n
              number of columns in matrix a
 7
       n1 -
    C
 8
       jc - work array used by this routine
    С
 9
    С
10
           real a(n,n1)
11
           integer jc(n)
12
    С
13
       assign a unit number to the output file
    С
           open(11,file='output')
14
15
    С
16
           do 70 i=1,n
17
           x=-1.
           m=i
18
           do 10 j=m,n
19
           if (abs(a(j,i)).lt.x) go to 10
20
21
           x=abs(a(j,i))
22
           1=j
23
    10 continue
24
              check matrix for singularity
25
           С
26
27
           jc(i)=114
           if (x) 20,90,20
28
    20 do 30 j=1,n1
29
30
           x=a(i,j)
31
           a(i,j)=a(l,j)
32
    30
        a(1,j)=x
33
           x=a(i,i)
34
           a(i,i)=1.
35
           do 40 j=1,n1
        a(i,j)=a(i,j)/x
do 60 j=1,n
36
    40
37
           if (j.eq.i) go to 60
38
39
           x=a(j,i)
40
           a(j,i)=0.
           do^{50} k=1, n1
41
42
    50
        a(j,k)=a(j,k)-x*a(i,k)
43
    60
        continue
        continue
44
45
           do 80 i3=1,n
46
           i=1+n-i3
47
           l=jc(i)
           do 80 j=1,n
x=a(j,i)
48
49
50
           a(j,i)=a(j,l)
51
    80 a(j,1)=x
52
           return
53
    90 write (11,100)
           jc(1)=-1
54
55
           return
56
    С
                           disaster - ill conditioned matrix')
           100 format ('
```

58 c 59 end NUMBER OF ERRORS = 0 NUMBER OF WARNINGS = 0

FORTRAN 77/UX HP92430A.07.04 COPYRIGHT HEWLETT-PACKARD CO. 1983. Thu Jul 26 14:20:19 1990

```
subroutine capoff
    С
 3
       FUNCTION:
    C
       Disables the 'caps' mode on the HP-2627A terminal.
 4
    C
 5
    C
 6
7
    C
    С
       D. Francis
 8
       Naval Biodynamics Laboratory
    С
 9
       New Orleans, Louisiana
    С
10
       28 June 1988
    С
11
12
           equivalence (ESCA, IEA), (AKO, IKO), (PP, IPP)
13
    С
           character*2 ESCA, AKO, PP
14
15
    С
16
           data IESCA/o'015446'/,K0/o'065460'/,IPSP/o'050040'/
17
    С
18
           call mvbits(IESCA, 0, 16, IEA, 16)
           call mvbits(K0,0,16,IK0,16)
19
           call mvbits(IPSP, 0, 16, IPP, 16)
20
21
    С
22
           write(6,10) ESCA, AKO, PP
23
    10
        format(6a2)
24
    С
25
           return
26
           end
NUMBER OF ERRORS = 0 NUMBER OF WARNINGS = 0
```

FORTRAN 77/UX HP92430A.07.04 COPYRIGHT HEWLETT-PACKARD CO. 1983. Thu Jul 26 14:20:19 1990

```
1
           subroutine caps
    С
 3
    С
       FUNCTION:
 4
    c Enables the 'caps' mode on the HP-2627A terminal.
    С
 6
7
    c BY:
    c D. Francis
 8
       Naval Biodynamics Laboratory
    С
 9
    С
       New Orleans, Louisiana
10
       28 June 1988
    C
11
    С
12
           equivalence (ESCA, IEA), (AK1, IK1), (PP, IPP)
13
   С
14
           character*2 ESCA, AK1, PP
15
    С
16
           data IESCA/o'015446'/,K1/o'065461'/,IPSP/o'050040'/
17
    С
18
           call mvbits(IESCA, 0, 16, IEA, 16)
19
          call mvbits(K1,0,16,IK1,16)
20
          call mvbits(IPSP, 0, 16, IPP, 16)
21 c
22
          write(6,10) ESCA, AK1, PP
23 10 format(6a2)
24
    С
25
           end
NUMBER OF ERRORS = 0 NUMBER OF WARNINGS = 0
```

FORTRAN 77/UX HP92430A.07.04 COPYRIGHT HEWLETT-PACKARD CO. 1983. Thu Jul 26 14:20:24 1990

```
subroutine cdntpt
 2
    C
       This subroutine calculates in anatomical coordinates the vector from
 3
    С
       instrument origin to the anatomical origin. It also generates the
 4
    С
       transformation matrix that take a vector from the instrumentation
 5
    C
       coordinate system to the anatomical coordinate system.
 6
    C
    С
 8
       input consist of common/blk1/arrays;
    С
 9
    C
       xh(3) = created in subroutine htrans and is the vector defining the
10
    С
       anatomical origin in lab coordinates.
11
    С
12
       ah(3,3) = created in the subroutine htrans and is the transformation
13
    C
       matrix that takes a vector from the lab into the anatomical
14
    С
15
       coordinate system.
    С
16
17
             = created in subroutine pobkg where it was called 'pp(i)';
18
   C
       vector defining the instrument origin in lab coordinates
19
    С
20
    C
       at(3,3) = created in subroutine pobkg where it was called 'a(3,3)';
21
    С
       transformation matrix that takes a vector from instruments
22
    С
23
       into the lab coordinate system.
    С
24
    С
25
    С
       Output consists of arrays
26
    С
27
       r(i) = r(i) + ah(i,j) * xh(k,j)
    С
       The instrument origin vector transformed into the head
28
    C
29
       anatomical coordinate system where
       xh(k,j) = xt(i)-xh(i) the vector from the
30
   С
31
       instrument origin to the anatomy origin in lab coordinates.
    С
32
33
       aa(i,j) = aa(i,j) + ah(i,k)*at(k,j)
    C
       where aa(i,j) = the transformation matrix that takes a
34
35
       vector in instrument coordinates and expresses it in
    C
       anatomy coordinates.
36
    С
37
    С
38
    C
39
           real aa(3,3), r(3)
40
           integer sday, syear, eday, eyear
           character*6 nsub, dat, blk
41
           character*6 not(9)
42
43
    С
           common /blk1/xh(3), ah(3,3), xt(3), at(3,3)
44
           common /c1/ nsub,nmnt,dat,blk,not,sday,syear,eday,eyear
45
46
    C
       assign a unit number to the output file
47
    C
           open(11, file='output')
48
49
           open(12, file='update')
50
    С
51
          write (11,100)
           do 10 i=1,3
52
53
          write (11,50) xh(i), (ah(i,j),j=1,3), xt(i), (at(i,j),j=1,3)
        xh(i)=xt(i)-xh(i)
54
55
          write (11,90)
56
          do 30 i=1,3
57
           r(i) = 0.
58
           do 20 j=1,3
```

```
59
              aa(i,j)=0.
60
              r(i)=r(i)+ah(i,j)*xh(j)
61
              do 20 k=1,3
          aa(i,j)=aa(i,j)+ah(i,k)*at(k,j)
write (11,60) r(i), (aa(i,j),j=1,3)
62
     20
63
64
65
             c write output data to update file
66
             С
67
             write(12,110) nsub,nmnt,dat,blk,(not(j),j=1,5),sday,s year,eday,
68
           *eyear
69
             write(12,80) (r(i),i=1,3)
70
             do 40 i=1,3
71
             write(12,70) (aa(j,i),j=1,3)
72
     40
         continue
73
             С
74
             return
75
     50 format (2(5x,f10.4,3x,3f10.8))
76
77
     60 format (5x, f10.4, 3x, 3f10.8)
78
     70 format (3(f10.8,2x))
79
     80 format (3(f10.6,2x))
     90 format (///12x,'instrumentation vs anatomy'/)
100 format (///18x,'anatomy vs lab',27x,'instrumentation vs lab'/)
110 format (a6,2x,i4,2x,2(a6,3x),5a6,4x,2(i3,i4))
80
81
82
83
84
             end
NUMBER OF ERRORS = 0 NUMBER OF WARNINGS = 0
```

FORTRAN 77/UX HP92430A.07.04 COPYRIGHT HEWLETT-PACKARD CO. 1983.

```
Thu Jul 26 14:20:25 1990
           subroutine htrans (x)
 2
    С
 3
        subroutine htrans
 4
    С
 5
    C
       This subroutine calculates the anatomical origin of the head
 6
    С
 7
        in lab coordinates and the transformation matrix which takes
    С
 8
        a vector in lab coordinates and transforms it into a vector
    С
 9
        in the head anatomical coordinate system.
10
    C
        input consist of:
11
    С
       x(3,13) = the lab coordinates of the 4 head anatomical bee bee's
12
       plus t3 t-plate bee bee's plus the 6 coordinates obtained
13
    С
       by performing a right-left/left-right switch of measure
14
    C
        defined locations of bee's bee's from the x-ray view.
15
        These are computed in subroutine pxryz by a least squares
16
    C
17
        technique.
    C
18
       xt(3t(3)) = created in subroutine pobkg where it was called 'pp(i)'
19
    С
        and and is the vector defining the instrument origin i
20
21
        lab coordinates.
    С
22
        at(3,3) = created in subroutine 'pobkg' where it was called 'a(3,3)'
23
    С
        and is the transformation matrix that takes a vector from
24
    C
25
        instrument trument into the lab coordinates system.
    C
26
    С
27
        output consist of:
    C
28
       xh(\bar{i}) = (x(i,2) + x(i,1))/2 = anat origin in lab.
    С
29
30
        ah(3,3) = is the transformation matrix which takes a vector in lab
        coordinates and transforms it into a vector in the head
31
    С
32
        anatomical system.
    С
33
           common /blk1/xh(3), ah(3,3), xt(3), at(3,3)
34
35
           real x(3,13)
36
           do 10 i=1,3
37
           xh(i) = (x(i,2)+x(i,1))/2.
           ah(1,i)=x(i,3)+x(i,4)-x(i,1)-x(i,2)
38
39
           ah(2,i)=x(i,2)+x(i,4)-x(i,1)-x(i,3)
40
           10 ah(3,i)=0.
           do 20 i=1,3
41
           ah(3,1)=ah(3,1)+ah(1,i)**2
42
           ah(3,2)=ah(3,2)+ah(2,i)**2
43
         ah(3,3)=ah(3,3)+ah(1,i)*ah(2,i)
44
    20
45
           ah(3,1) = sqrt(ah(3,1))
           ah(3,2) = sqrt(ah(3,2))
46
           ah(3,3)=ah(3,3)/(ah(3,1)*ah(3,2))

r=1./(sqrt(1.-ah(3,3)**2)*ah(3,2))
47
48
49
           do 30 i=1,3
50
           ah(1,i)=ah(1,i)/ah(3,1)
         ah(2,i)=r*(ah(2,i)-ah(3,2)*ah(3,3)*ah(1,i))
51
    30
           ah(3,1)=ah(1,2)*ah(2,3)-ah(1,3)*ah(2,2)

ah(3,2)=ah(2,1)*ah(1,3)-ah(1,1)*ah(2,3)
52
53
           ah(3,3)=ah(1,1)*ah(2,2)-ah(1,2)*ah(2,1)
54
55
           return
56
    С
           end
57
```

NUMBER OF ERRORS = 0 NUMBER OF WARNINGS = 0

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```
1
       main and zz03 updated 9/4/80 by p. shimp to handle
 2
       processing of a-plates
    С
 3
    С
 4
           common /blk1/xh(3),ah(3,3),xt(3),at(3,3)
 5
           common \frac{b1k2}{xo(3,2)}, xs(3,2), c(3,3,2)
 6
           common /c1/ nsub,nmnt,dat,blk,not,sday,syear,eday,eyear
 7
    С
 8
           character*6 ksubj,nsub,dat,blk
 9
           character*6 not(9)
10
           character*1 pcode
11
           real w(3), p(4), pp(3,4)
12
           integer jp(3)
13
           real xp(2,2), x(3,13), xx(3)
           real xtp(4) real sp(2,2,13), er(13)
14
15
           real xk(3,3), x1(3,3), x2(3,3)
16
17
           real xpn(6)
18
    С
19
       the variables day and year refer to date of x-ray
    С
20
       integer day, year
21
       The variables sday, syear, eday & eyear
    C
       are the start date and end date for the data.
22
    С
23
       integer date, sday, syear, eday, eyear
24
    С
25
           real spi(4,13)
26
           equivalence (sp(1,1,1), spi(1,1))
27
    C
28
           data x1 /0.,0.,0.,6.286,-6.286,0.,6.286,6.286,0./
29
           data x2 /-.3556,0.,.175,5.9304,-6.286,.175,5.9304,6.2 86,.175/
30
    С
31
    С
       assign a unit number to the input and output files
           open(10, file='input')
32
33
           open(11, file='output')
34
    C
35
    10 continue
36
    C
       put terminal in 'caps' mode.....
37
    С
38
           call caps
39
    C
40
       request user input.....
    С
41
    С
42
           write(6,*) 'enter subject number (a6 format)'
43
           read(5,536) nsub
44
           write(6,*) 'enter date of xray (MON YR a6 format)'
45
           read(5,536) dat
           write(6,*) 'enter Julian date of xray (i5 format)'
46
47
           read(5,565) idate
48
    С
    c....read data from input file ......
49
50
    С
51
           read(10,535) ksubj,date,mmount,nmount,sday,syear,eday ,eyear
52
53
    С
54
    c....check for correct input data.....
55
           if(ksubj.ne.nsub) go to 525
56
           if (date.ne.idate) go to 12
57
           go to 18
58
   12 write(6,15)
```

```
15 format ('Dates do not match. Enter Y to continue, N to stop.')
59
60
           read(5,540) pcode
           if (pcode.ne.'Y') go to 530
61
62
    18 continue
63
    C
64
    c....initialize the variable 'blk'
65
           blk='
66
    С
67
           c.....process the data......
68
    C
69
           write(6,*) 'enter pcode (A for a-plate or T for t-plate)'
           read (5,540) pcode
70
           if (pcode.ne.'A'.and.pcode.ne.'T') print 550 if (pcode.ne.'A'.and.pcode.ne.'T') stop 1
71
72
           write(6,*) 'enter xray Julian date'
73
           read (5,545) day, year
74
75
           d=year*1000+day
76
           do 30 i=1,3
77
           do 30 j=1,3
           if (pcode.eq.'A') go to 20
78
79
           xk(i,j)=x1(i,j)
           go to 30
80
81
    20
        xk(i,j)=x2(i,j)
82
    30
        continue
           if (pcode.ne.'A') go to 35
83
        in the event x-ray was taken after jan 1,1981 change z component
84
       to.238 for A plates only
85
    C
86
           if (d.lt. 81001) go to 35
87
           do 32 i=1,3
88
           xk(3,i)=.238
89
           32
               continue
90
    35
        call prism2 (xo,xs,c)
91
    40
        write(6,555)
92
           read(5,560) jo,kk
93
           if(kk.eq.9) go to 530
94
           if(kk.eq.7) go to 10
95
           if (kk.eq.3) go to 220
96
           if (kk.eq.4) go to 450
97
    C
98
    c.....mouth data calculations
99
    С
            write(6,*) 'enter comments for head data (9a6 format)'
100
            read(5,575) not
101
102
            nmnt=mmount
            write (11,580) write (11,590) nsub,nmnt,dat,(not(j),j=1,9)
103
104
105
            write(11,630)
106
            write(11,640)
107
            write(11,650)
108
            write(11,660)
109
            write(11,820)
110
            write(11,670)
111
     С
112
            do 50 j=1,4
113
            read(10,620) (spi(j,i), i=1,7)
114
            do 50 i=1,7
115
            spi(j,i)=spi(j,i)*2.54
116
     50
         continue
117
            С
               interchange ltp and rtp coordinates when processing a-plate
118
            С
            if (pcode.ne.'A') go to 70
119
120
            do 60 j=1,4
```

```
121
            t=spi(j,6)
122
            spi(j,6)=spi(j,7)
            spi(j,7)=t
123
124
     60
         continue
125
     70 continue
126
            call rlswch (1,8,sp)
127
            call rlswch (3,10,sp)
128
            call rlswch (6,12,sp)
            do 210 i=1,13
129
130
            call pxry2 (x(1,i),sp(1,1,i),er(i),xtp)
131
            if (i.eq.1) go to 80
132
            if (i.eq.2) go to 90
133
            if
                (i.eq.3) go to 100
134
            if
                (i.eq.4) go to 110
135
            if
               (i.eq.5) go to 120
136
            if (i.eq.6) go to 130
137
            if (i.eq.7) go to 140
138
            if (i.eq.8) go to 150
                (i.eq.9) go to 160
139
            if
140
            if
               (i.eq.10) go to 170
141
            if (i.eq.11) go to 180
142
            if (i.eq.12) go to 190
143
            if (i.eq.13) go to 200
144
     80
         write (11,680) (spi(j,i), j=1,4), (x(ii,i),ii=1,3), er(i)
145
            go to 210
146
     90
         write(11,690) (spi(j,i),j=1,4),(x(ii,i),ii=1,3),er()
147
            go to 210
     100
148
          write(11,700) (spi(j,i), j=1,4), (x(ii,i), ii=1,3), er(i)
149
            go to 210
150
     110
          write(11,710) (spi(j,i),j=1,4),(x(ii,i),ii=1,3),er(i)
151
            go to 210
152
          write(11,720) (spi(j,i),j=1,4),(x(ii,i),ii=1,3),er(i)
     120
153
            go to 210
154
     130
          write(11,730) (spi(j,i), j=1,4), (x(ii,i), ii=1,3), er(i)
155
            go to 210
156
     140
          write (11,740) (spi(j,i), j=1,4), (x(ii,i), ii=1,3), er(i)
157
            go to 210
158
     150
          write(11,750)
159
            write (11,760) (spi(j,i), j=1,4), (x(ii,i),ii=1,3), er(i)
160
            go to 210
161
     160
          write (11,770) (spi(j,i), j=1,4), (x(ii,i), ii=1,3), er(i)
162
            go to 210
     170
          write(11,780) (spi(j,i), j=1,4), (x(ii,i), ii=1,3), er(i)
163
164
            go to 210
165
     180
          write (11,790) (spi(j,i), j=1,4), (x(ii,i),ii=1,3), er(i)
166
            go to 210
167
          write (11,800) (spi(j,i),j=1,4),(x(ii,i),ii=1,3),er(i)
     190
168
            go to 210
169
     200
          write(11,810) (spi(j,i),j=1,4),(x(ii,i),ii=1,3),er(i)
170
     210
          continue
171
            call option (1,8,er,x,jo)
172
            call option (3,10,er,x,jo)
173
            call option (6,12,er,x,jo)
174
            if (pcode.eq.'A') write(11,850)
            call pobkg (x(1,5),xk,3,xt,at) call htrans (x)
175
176
            write (11,580)
177
178
            write (11,600) nsub, nmnt, dat
179
            write (11,610) (not(j),j=1,9)
180
            call cdntpt
181
            if (kk.eq.2) go to 40
182
```

```
c....neck data calculations
183
184
     220 continue
185
186
            nmnt=nmount
187
            write(6,*) 'enter comments for neck data (9a6 format)'
            read(5,575) not
188
189
            write(6,*) 'enter block or noblock (a6 format)'
190
            read(5,536) blk
191
            write (11,860)
192
            write (11,600) nsub, nmnt, dat
193
            write (11,610) (not(j),j=1,9)
194
     С
195
     c....read the required data
196
     С
            do 230 j=1,4
197
198
            read(10,620) (spi(j,i),i=1,5)
            do 230 i=1,5
199
200
            spi(j,i) = spi(j,i) *2.54
     230
201
           continue
202
            call rlswch (4,6,sp)
203
            sc1=0.
204
            sc2=0.
205
            write(11,630)
206
            write(11,640)
207
            write(11,650)
208
            write(11,660)
209
            write(11,820)
210
            write(11,670)
211
            do 310 i=1,7
            call pxry2 (x(1,i),sp(1,1,i),er(i),xtp)
if (i.gt.5) sc2=sc2+sp(2,2,i)-xtp(4)
212
213
214
            if (i.eq.4.or.i.eq.5) sc2=sc2-sp(2,2,i)+xtp(4)
215
            if (i.lt.6) sc1=sc1+sp(2,2,i)-xtp(4)
216
            if (i.eq.1) go to 240
217
            if (i.eq.2)
                         go to 250
218
            if (i.eq.3) if (i.eq.4)
                         go to 260
219
                         go to 270
220
            if (i.eq.5) go to 280
221
            if (i.eq.6) go to 290
222
            if (i.eq.7) go to 300
223
     240
          write (11,870) (spi(j,i), j=1,4), (x(ii,i),ii=1,3), er(i)
224
            go to 310
225
     250
          write (11,880) (spi(j,i), j=1,4), (x(ii,i),ii=1,3), er(i)
226
            go to 310
     260
227
          write(11,890) (spi(j,i), j=1,4), (x(ii,i), ii=1,3), er(i)
228
            go to 310
229
     270
          write(11,900) (spi(j,i), j=1,4), (x(ii,i), ii=1,3), er(i)
230
            go to 310
231
     280
          write(11,910) (spi(j,i), j=1,4), (x(ii,i), ii=1,3), er(i)
232
            go to 310
233
     290
          write(11,750)
234
            write(11,920) (spi(j,i), j=1,4), (x(ii,i), ii=1,3), er(i)
235
            go to 310
236
     300
          write(11,930) (spi(j,i),j=1,4), (x(ii,i),ii=1,3),er(i)
237
     310
          continue
238
            call option (4,6,er,x,jo)
            ai=er(4)**2+er(5)**2-er(6)**2-er(7)**2
239
240
            if (ai.gt.0.) sc1=sc1+sc2
241
            call pobkg (x(1,3),xk,3,xt,at)
            read(10,620) xp
242
243
            do 320 i=1,2
            do 320 j=1,2
244
```

```
245
                            xp(i,j)=xp(i,j)*2.54
                            320 continue
246
247
                            write (11,940) xp
248
                            ah(1,1) = -xs(3,1) * (xp(2,2) - xp(2,1))
                            ah(1,2)=xs(3,1)*(xp(1,2)-xp(1,1))
249
250
                            ah(1,3) = (xs(1,1) - xp(1,1)) * (xp(2,2) - xp(2,1)) - (xs(2,1) - xp(2,1)) * (xp(2,2) - xp(2,2)) + (xp(2,2) - xp(2,2)) * (xp(2,2) - xp(2,2)) + (xp(2,2) - xp(2,2)) * (xp(2,2) - xp(2,2)) + (xp(2,2) - xp(2,2)) * (xp(2,2) -
251
                      11,2) - xp(1,1)
                            do 330 i=1.3
252
253
                            xx(i)=x(i,2)-x(i,1)
254
                            ah(3,i)=0.
255
                            do 330 j=1,3
256
                            330 ah(3,i)=c(j,i,1)*ah(1,j)+ah(3,i)
257
                            ah(2,1)=ah(3,2)*xx(3)-ah(3,3)*xx(2)
258
                            ah(2,2)=ah(3,3)*xx(1)-ah(3,1)*xx(3)
259
                            ah(2,3)=ah(3,1)*xx(2)-ah(3,2)*xx(1)
260
                            ai=0.
261
                            do 340 i=1.3
262
            340 ai=ai+ah(2,i)**2
263
                            ai=sqrt(ai)
                            do 350 i=1,3
1 350 ah(2,i)=ah(2,i)/ai
264
265
266
            С
                            read(10,620) (xpn(k),k=1,6)
267
268
                            xp(1,1)=xpn(1)
269
                            xp(2,1)=xpn(2)
270
                            xp(1,2) = (xpn(3) + xpn(5))/2.0
271
                            xp(2,2) = (xpn(4) + xpn(6))/2.0
272
273
                            do 360 i=1,2
            do 360 j=1,2
274
275
                            xp(i,j)=xp(i,j)*2.54
            360 continue
276
277
                            write (11,960) xp
                            do 370 ill=1,2
278
279
                            370 xp(2,ill)=xp(2,ill)-sc1/5.
280
                            q1 = 0.
                            do 390 i=1,3
281
282
                            g3=x(i,1)
283
                            xx(i)=0.
284
                            do 380 j=1,3
                            xx(i)=xx(i)+ah(2,j)*c(i,j,2)
285
286
            380
                        g3=g3+c(j,i,2)*(xo(j,2)-xs(j,2))
287
            390
                        g1=g1+g3*ah(2,i)
288
                            do 420 i=1,2
289
                            ga=g1/((xp(1,i)-xs(1,2))*xx(1)+(xp(2,i)-xs(2,2))*xx(2)-xs(3,2)*x
290
                            1x(3)
291
                            do 400 j=1,2
                        x(j,8)=ga*(xp(j,i)-xs(j,2))+xs(j,2)
292
293
                            x(3,8) = (1.-ga) *xs(3,2)
294
                            l=i+5
295
                            do 410 j=1,3
296
                            x(j,1)=0.
297
                            do 410 k=1,3
298
            410
                        x(j,1) = (x(k,8)-xo(k,2))*c(k,j,2)+x(j,1)
299
            420
                        write (11,970) (x(j,1),j=1,3)
300
                            ai=0
301
                            do 430 i=1,3
                            xh(i)=x(i,6)
302
303
                            ah(1,i)=xh(i)-x(i,7)
304
            430
                        ai=ai+ah(1,i)**2
305
                            ai=sqrt(ai)
306
                            do 440 i=1,3
```

```
440 ah(1,i)=ah(1,i)/ai
307
             ah(3,1)=ah(1,2)*ah(2,3)-ah(1,3)*ah(2,2)
308
            ah(3,2)=ah(2,1)*ah(1,3)-ah(1,1)*ah(2,3)
309
310
            ah(3,3)=ah(1,1)*ah(2,2)-ah(1,2)*ah(2,1)
311
            write (11,860)
312
            write (11,600) nsub, nmnt, dat
313
            write (11,610) (not(j),j=1,9)
314
            call cdntpt
315
            go to 40
316
317
     c....pelvic data calculations
318
     450 continue
319
            write (11,980)
320
321
            do 460 k=1,4
322
323
     460 pp(j,k)=0.
     470 \text{ do } 480 \text{ j}=1,4
324
          read (10,620) (spi(j,i),i=1,6)
325
     480
326
            do 490 i=1.4
            write (11,840) i,(spi(j,i),j=1,4)
call pxry2 (x(1,i),sp(1,1,i),er(i),xtp)
327
328
329
     490
           write (11,830) (x(ii,i),ii=1,3),er(i)
            call htrans (x)
330
331
            do 520 i=1,2
332
            p(1) = (sp(2,i,6) - sp(2,i,5)) *xs(3,i)
            p(2) = (sp(1,i,5) - sp(1,i,6)) *xs(3,i)
333
            p(3) = (sp(1,i,5)-xs(1,i))*(sp(2,i,6)-xs(2,i))-(sp(2,i,5)-xs(2,i))
334
            1*(sp(1,i,6)-xs(1,i))
335
336
            p(4) = 0.
            do 500 j=1,3
337
            p(4) = p(\bar{4}) + p(j) * (xs(j,i) - xo(j,i))
338
339
            w(j)=0.
340
            do 500 k=1,3
341
     500 w(j)=w(j)+p(k)*c(k,j,i)
            do 510 j=1,3
p(4)=p(4)-w(j)*xh(j)
342
343
344
            p(j)=0.
345
            do 510 k=1,3
346
     510 p(j)=p(j)+ah(j,k)*w(k)
            write (11,990) p
do 520 k=1,3
347
348
            do 520 j=1,4
349
           pp(k,j)=pp(k,j)+p(k)*p(j)
read (5,1000) jj
350
     520
351
352
353
             if (jj.ne.0) go to 470
             call axeb (pp,3,4,jp)
354
            write (11,1010) (pp(j,4),j=1,3)
355
            go to 40
356
357
     c....Output error message.....
358
359
     525 write(6,*) 'Incorrect Subject Id - Processing Stopped'
360
     530 call capoff
361
362
            stop
363
364
     535 format (a6,1x,i5,1x,2(i4,1x),2(i3,i4))
365
     536 format(a6)
     540 format (a1)
366
367
     545 format(i3,i2)
     550 format (1x, 'plate code invalid, check first input card'/1x, 'it
```

```
369
           1should contain an a or t in column 1')
370
      555 format('enter option code jo and processing code kk (2i1) format'/
           *'jo = 1 to exercise the option (standard operation -always 1)'/
371
           *'jo = any other number not to exercise the option'/
372
373
           *'kk = 1 process head and neck data'/
374
          *'kk = 2 process head data only'/
375
          *'kk = 3 process neck data only'/
376
          *'kk = 4 process pelvic data only'/
           *'kk = 7 redo program'/
377
           *'kk = 9 end program')
378
      560 format (2i1)
379
      565 format (i5)
380
381
      570 format (a6, i4, 10a6)
382
      575 format (9a6)
      580 format ('1 head anatomical to tee-plate transformation ')
383
      590 format ('
                       subject ',a6,' mount ',i4,' date ',a6,' notes '
384
385
          19a6)
386
      600 format ('
                      subject ',a6,' mount ',i4,' date ',a6)
387
      610 format (10x,' notes
                                   ',9a6)
      620 format (7(f7.3,1x))
388
      630 format (1h0,'bee bee id i measured x-ray coordinates
389
     1 i lab coordinates i sum of the squares of the')
640 format (12x,'i',42x,'i',31x,'i difference between the')
650 format (12x,'i',42x,'i',31x,'i measured and best estimate')
660 format (12x,'i',8x,'ap',19x,'lat',10x,'i',31x,'i of x-ray coordin
390
391
392
393
394
          1ates')
395
      670 format
                   (1h0,11x,'i',4x,'x',10x,'y',10x,'x',8x,'y',6x'i',4x,'x',9x
          1,'y',9x,'z',6x,'i',4x,'e')
396
397
      680 format (1h, 1x, '1 r.audit
                                        ', f8.4, 2x, f8.4, 4x, f8.4, 2x, f8.4, 4x, f8.4,
398
          12x, f8.4, 2x, f8.4, 4x, f8.4)
399
      690 format (2x,'2 1.audit
                                     ',f8.4,2x,f8.4,4x,f8.4,2x,f8.4,4x,f8.4,2x,f
400
          18.4,2x,f8.4,4x,f8.4)
401
      700 format (2x, '3 r.orbit)
                                     ', f8.4, 2x, f8.4, 4x, f8.4, 2x, f8.4, 4x, f8.4, 2x, f
          18.4,2x,f8.4,4x,f8.4)
402
403
      710 format (2x,'4 l.orbit
                                     ', f8.4, 2x, f8.4, 4x, f8.4, 2x, f8.4, 4x, f8.4, 2x, f
404
          18.4,2x,f8.4,4x,f8.4)
405
     720 format (2x,'5 c.t-plt
                                     ', f8.4, 2x, f8.4, 4x, f8.4, 2x, f8.4, 4x, f8.4, 2x, f
406
          18.4,2x,f8.4,4x,f8.4)
407
      730 format (2x,'6 r.t-plt
                                     ', f8.4, 2x, f8.4, 4x, f8.4, 2x, f8.4, 4x, f8.4, 2x, f
408
          18.4,2x,f8.4,4x,f8.4)
409
     740 format (2x,'7 l.t-plt
                                    ', f8.4, 2x, f8.4, 4x, f8.4, 2x, f8.4, 4x, f8.4, 2x, f
410
          18.4,2x,f8.4,4x,f8.4
411
     750 format (1h0,14x,'right/left switch follow below')
     760 format (1h0,1x,'8 r.audit 12x,f8.4,2x,f8.4,4x,f8.4)
412
                                        ',f8.4,2x,f8.4,4x,f8.4,2x,f8.4,4x,f8.4,
413
414
     770 format (2x,'9 l.audit
                                     ',f8.4,2x,f8.4,4x,f8.4,2x,f8.4,4x,f8.4,2x,f
          18.4, 2x, f8.4, 4x, f8.4
415
416
     780 format (1x,'10 \text{ r.orbit})
                                      ', f8.4, 2x, f8.4, 4x, f8.4, 2x, f8.4, 4x, f8.4, 2x,
          1f8.4,2x,f8.4,4x,f8.4)
417
     790 format (1x,'11 1.orbit
418
                                      ',f8.4,2x,f8.4,4x,f8.4,2x,f8.4,4x,f8.4,2x,
          1f8.4,2x,f8.4,4x,f8.4)
419
420
     800 format (1x,'12 r.t-plt
                                      ', f8.4, 2x, f8.4, 4x, f8.4, 2x, f8.4, 4x, f8.4, 2x,
421
          1f8.4,2x,f8.4,4x,f8.4)
422
     810 format (1x,'13 l.t-plt
                                      ', f8.4, 2x, f8.4, 4x, f8.4, 2x, f8.4, 4x, f8.4, 2x,
423
          1f8.4,2x,f8.4,4x,f8.4)
     820 format (12x,'i',42x,'i',31x,'i')
424
     830 format (5x, 4f15.4)
425
426
     840 format (1h0,2x,i2,4f15.4)
427
     850 format (///1x,'note:when processing data from a-plate, ltp and rtp
428
          1'1x,'are interchanged from the way in which they were entered to'/
429
          25x, 'account for position of a-plate ')
430
     860 format ('1 t-1 anatomical to tee-plate transformation ')
```

```
870 format (1h0,1x,'1 p-spine ',f8.4,2x,f8.4,4x,f8.4,2x,f8.4,4x,f8.4,
431
      12x, f8.4, 2x, f8.4, 4x, f8.4)
880 format (2x, '2 s-notch ',
432
                                       ', f8.4, 2x, f8.4, 4x, f8.4, 2x, f8.4, 4x, f8.4, 2x, f
433
434
           18.4,2x,f8.4,4x,f8.4)
      890 format (2x,'3 c.t-plt
                                       ',f8.4,2x,f8.4,4x,f8.4,2x,f8.4,4x,f8.4,2x,f
435
           18.4,2x,f8.4,4x,f8.4)
436
                                       ', f8.4, 2x, f8.4, 4x, f8.4, 2x, f8.4, 4x, f8.4, 2x, f
      900 format (2x,'4 r.t-plt
437
438
           18.4,2x,f8.4,4x,f8.4)
                                       ', f8.4, 2x, f8.4, 4x, f8.4, 2x, f8.4, 4x, f8.4, 2x, f
439
      910 format (2x, '5 l.t-plt
           18.4,2x,f8.4,4x,f8.4)
440
      920 format (1h0,1x,'6 r.t-plt ',f8.4,2x,f8.4,4x,f8.4,2x,f8.4,4x,f8.4,
441
           12x, f8.4, 2x, f8.4, 4x, f8.4)
442
      930 format (2x,'7 1.t-plt
                                       ', f8.4, 2x, f8.4, 4x, f8.4, 2x, f8.4, 4x, f8.4, 2x, f
443
           18.4,2x,f8.4,4x,f8.4)
444
      940 format (22h0 articular facets,4f10.4)
960 format (23h0 lateral projection,4f10.4)
445
446
      970 format (5x,3f15.4)
447
      980 format ('1 c.g. routine')
990 format (5x,4f14.6)
448
449
450
     1000 format (i2)
1010 format (5x,3f14.6)
451
     1020 format (a6, i5, a5, i2, 2i7, 20f7.3)
452
453
      C
454
             end
```

FORTRAN 77/UX HP92430A.07.04 COPYRIGHT HEWLETT-PACKARD CO. 1983. Thu Jul 26 14:20:55 1990 subroutine option (j,k,er,x,jo) 2 C 3 С subroutine option 4 5 C This subroutine compares the residual error associated with the С 7 measured definition of the location of right and left bee bee's, with С 8 C the errors associated with subroutine rlswch's definition of right 9 С and left bee bee's. Finally it states the option with least error and 10 С if told to do so will exercise the option. 11 12 С The options are option j vs. k not indicated
 option j vs. k indicated but ignored 13 С 14 С 15 3. option j vs. k indicated and exercised 16 C 17 C Input consist of 18 j = the number of the right-side bee bee's as obtained from С 19 lateral view measurements C 20 С 21 k = the number of the right-side bee bee's so labeled by 22 subroutine rlswch has identical x-ray coordinates as the С 23 measured labeled left side bee bee C 24 С 25 C er = the sum of the squares of the difference between the 26 С 'measured' and 'calculated' ap and lateral x-ray 27 coordinates of the bee bee under scrunity. С 28 C 29 calculated in subroutine pxryz and is the best least squares С 30 lab coordinates for the bee bee under scrutiny. C 31 С 32 С jo = code which determines if an option is to be exercised. 33 C 34 C 35 real x(3,13), er(13) 36 C 37 С assign a unit number to the output file 38 open(11,file='output') 39 С 40 r=er(k)*er(k)+er(k+1)*er(k+1)-er(j)*er(j)-er(j+1)*er(j+1)if (r.gt.0.) go to 30 if (jo.ne.1) go to 20 41 42 43 write (11,40) j,k 44 1 = j + 145 do 10 i=1,346 x(i,j)=x(i,k)47 10 x(i,1)=x(i,k+1)48 return 49 20 write (11,50) j,k 50 return 51 30 write (11,60) j,k 52 return 53 40 format (9h option,i2,4h vs,i2,24h indicated and exercised) 55 50 format (9h option, i2, 4h vs, i2, 23h indicated but ignored) 56 60 format (9h option, i2, 4h vs, i2, 15h not indicated) 57 С end NUMBER OF ERRORS = 0 NUMBER OF WARNINGS = 0

FORTRAN 77/UX HP92430A.07.04 COPYRIGHT HEWLETT-PACKARD CO. 1983. Thu Jul 26 14:20:57 1990

```
subroutine pobkg (x,xx,ii,pp,a)
1
 2
    C
3
       subroutine pobkg
 4
    С
 5
    C
 6
7
       This subroutine calculates the vector defining the
    С
       instrument origin pp lab coordinates and also calculates
    С
 8
       the transformation matrix [instr/lab]
    С
 9
       a(i,j) = at(i,j) of main program.
10
    C
11
       input consist of:
    С
       x(3,3) = best least squares coordinates of the center, right,
12
    Ç
                  and left t-plate bee bee's in the lab coordinate
13
    C
                  system as calculated in subroutine pxryz
14
    С
15
    C
       ii
                = 3 the number of bee bee's on the t-plate
16
    C
17
    C
       xx(3,3) = xk in main program and is the location of the 3
18
    С
19
                  instrument bee bee's in the instrument coordinate system.
    C
20
21
       output consist of:
    C
22
                = vector defining the instrument origin in lab coordinates
    С
       pp(i)
23
                  also xt(i) in the main program and in subroutine cdntpt
24
    С
25
               = transformation matrix which takes a vector from the
    C
       a(i,j)
26
                  instrument coordinate system and puts it in the lab
    C
                  coordinate system. Also called at(j,j) in the main program
27
    С
28
    С
29
           real xp(3)
30
           real x(3,3), xx(3,3), pp(3), a(3,3), xm(3,3)
31
    С
32
    C
       assign a unit number to the output file
33
           open(11, file='output')
34
    C
35
           write(11,440)
           write(11,120)
36
37
           write(11,130)
38
           write(11,140)
39
          write(11,150)
40
          write(11,160)
          write(11,170)
41
42
          write(11,180)
43
          write(11,190)
44
          write(11,200)
45
          write(11,210)
          write(11,220)
46
47
           write(11,230)
48
           write(11,240)
49
          write(11,250)
50
          write(11,260)
51
          write(11,270)
52
          write(11,280)
53
           write(11,290)
54
          write(11,300)
55
          write(11,310)
56
           write(11,320)
57
           write(11,330)
58
           write(11,340)
```

```
59
           write(11,350)
60
           write(11,360)
61
           write(11,370)
62
           write(11,380)
63
           write(11,390)
64
           write(11,400)
65
           write(11,410)
66
           write(11,420)
           write(11,430)
67
68
           write(11,110) xx
69
    С
70
71
           do 20 i=1,3
72
           xp(i)=0.
73
           pp(i)=0.
74
           do 10 j=1,ii
75
           pp(i)=pp(i)+x(i,j)
76
    10
       xp(i)=xp(i)+xx(i,j)
77
           xp(i)=xp(i)/float(ii)
78
    20
         pp(i)=pp(i)/float(ii)
79
           do 40 i=1,3
80
           do 30 j=1,3
81
           a(i,j)=0.
           xm(i,j)=0.
do 30 k=1,ii
82
83
84
         xm(i,j)=xm(i,j)+(x(i,k)-pp(i))*(xx(j,k)-xp(j))
85
    40
         a(i,i)=1.
           do 80 ijk=1,10
86
87
           w=atan2((xm(3,2)-xm(2,3)),(xm(2,2)+xm(3,3)))
88
           c=cos(w)
89
           s=sin(w)
90
           do 50 k=1,3
91
           r=a(2,k)
92
           a(2,k)=c*r-s*a(3,k)
93
           a(3,k)=s*r+c*a(3,k)
94
           r=xm(k,2)
95
           xm(k,2)=c*r-s*xm(k,3)
96
    50 xm(k,3)=s*r+c*xm(k,3)
97
           w=atan2((xm(1,3)-xm(3,1)),(xm(1,1)+xm(3,3)))
98
           c=cos(w)
99
           s=sin(w)
100
            do 60 k=1,3
101
            r=a(1,k)
102
            a(1,k)=c*r+s*a(3,k)
103
            a(3,k)=c*a(3,k)-s*r
104
            r=xm(k,1)
105
            xm(k,1)=c*r+s*xm(k,3)
            60 xm(k,3)=c*xm(k,3)-s*r
106
            w=atan2((xm(2,1)-xm(1,2)),(xm(1,1)+xm(2,2)))
107
108
            c=cos(w)
109
            s=sin(w)
110
            do 70 k=1,3
111
            r=a(1,k)
112
            a(1,k)=c*r-s*a(2,k)
113
            a(2,k)=c*a(2,k)+s*r
114
            r=xm(k,1)
115
            xm(k,1)=c*r-s*xm(k,2)
     70 xm(k,2)=c*xm(k,2)+s*r
116
117
            r = (abs(xm(2,3)-xm(3,2))+abs(xm(1,2)-xm(2,1))+abs(xm(1,3)-xm(3,1))
118
            1))/(xm(1,1)+xm(2,2)+xm(3,3))
119
            if (r.ge.0..and.r.lt..000001) go to 90
120
     80
         continue
```

```
121
        90 do 100 i=1,3
122
                  do 100 j=1,3
123
       100 pp(i) = pp(i) - a(i, j) * xp(j)
124
                  return
125 c
       110 format (///60x,'x y z'//48x,'bb 1 ',3f9.4//6x,'loca
126
              ion of bee bees in instrumentation: bb 2 ',3f9.4//48x,'bb 3 ',
127
                  3f9.4)
128
        120 format (//50x,'/----\')
129
       130
131
132
133
134
135
136
       210 format (34x,'/',41x,'\')
210 format (34x,'/',41x,'\')
220 format (33x,'//',6x,'/----\',7x,'----',5x,'/----\',6x,'\\')
230 format (33x,'/',6x,'1',6x,'1',6x,'1++1',4x,'1',6x,'1',5x,'\\')
240 format (9x,'+ z out of paper',7x,'/',7x,'\----/',7x,'1++1',5x,'\
',7x,'\',12x,'\')
250 format (22x,'/')
137
138
139
140
141
142
        250 format (32x,'//',20x,'1+1+1------ + Y
143
144
              direction')
       260 format (32x,'1',21x,'1+++1',19x,'\',11x,'/')
270 format (32x,'1',21x,'1 1 1',19x,'1')
280 format (32x,'1',21x,'1 1 1',19x,'1')
145
146
147
       280 rormat (32x,'1',21x,'1 1 1',19x,'1')
290 format (32x,'1',21x,'1 1 1',19x,'1')
300 format (32x,'1',21x,'1 1 1',19x,'1')
310 format (33x,'\',20x,'1 1 1',19x,'/')
320 format (54x,'1 1 1',18x,'/')
330 format (54x,'1 1 1')
340 format (54x,'1 1 1')
350 format (34x,'1 1 1')
148
149
150
151
152
153
       154
155
156
157
158
       400 format (5(56x,'1'/),56x,'1')
410 format (54x,'\ 1 /')
420 format (55x,'\1/')
430 format (53x,'+ x direction')
440 format (11,'plexiglass t-plate coordinate system-orientation and
159
160
161
162
163
               ocation of bee bees')
164
165
        С
166
                  end
NUMBER OF ERRORS = 0 NUMBER OF WARNINGS = 0
```

FORTRAN 77/UX HP92430A.07.04 COPYRIGHT HEWLETT-PACKARD CO. 1983. Thu Jul 26 14:21:16 1990

```
1
           subroutine prism2 (xop,xsp,cp)
    C
 3
    С
 4
    С
       This subroutine establishes the lab coordinate system and
       calculates both the ap and lateral camera orientations and
 5
 6
    С
       positions in the lab.
    C
 8
       Inputs are all initial guesses
    С
 9
       xo = vector from lab to x-ray origin in x-ray coordinates
    С
10
       xs = vector from source origin to x-ray origin in x-ray coordinates
11
    С
12
    С
13
    С
       c = transformation matrix from [lab/xray]?
14
    С
15
       Outputs are the best estimates of the three inputs above?
    С
16
    C
17
18
    С
19
    С
       Revised December 1987
20
21
       The following assumptions were made:
    C
22
    C
23
    C
        (1) xs is the same for ap and lateral calibration and is
           constant for all runs.
24
    С
25
    С
           The value of xs: 0.0, 0.0, 150.
26
    С
        (2) xo is different for ap and lateral calibration but is
27
    С
28
    С
           constant for all runs.
29
    С
           The values of xo are: (ap) 20., 0.0, 10.; (lat) 0.0, 0.0, 10.
30
    C
31
       (3) c is different for ap and lateral calibrations but is
    С
32
    С
           constant for all runs.
33
    С
           The values of c are:
34
    C
       (ap) (lat)
                   35
    С
                                                             0.0, 0.0, 1.0
36
                                                             1.0, 0.0, 0.0
0.0, 1.0, 0.0
    С
37
    C
38
39
    c*IF ANY OF THESE ASSUMPTIONS ARE WRONG, THIS ROUTINE MUST BE MODIFIED*
40
41
    С
42
    C
43
           real xop(3,2), xsp(3,2), cp(3,3,2), xpp(2,13,2), pxp(2,2)
44
           real xt(3,13), a(9,10), xp(2,13), c(3,3), xo(3), xs(3), rt(3)
45
           real w(10), cc(3,3), xxo(3), xxs(3)
46
           integer ja(9)
47
    С
48
           data cc /-1.0,0.0,0.0,0.0,0.0,1.0,0.0,1.0,0.0/
49
          data xxo /20.0,0.0,10.0/
50
          data xxs /0.0,0.0,150.0/
51
          data xt /5.08,0.,5.08,25.4,0.,5.08,25.4,0.,25.4,5.08,0.,25.4,0.,6.
        20,25.4,0.,5.08,5.08,0.,25.4,5.08,0.,25.4,25.4,5.08,25.4,15.24,15.
52
        24,15.24,15.24,25.4,5.08,15.24,15.24,15.24,5.08,15.24,15.24,25.4/
53
54
55
    9
       format(3(f7.3,2x))
56
   С
57
       assign a unit number to the input file
58
          open(10, file='input')
```

```
open(11, file='output')
59
60
    С
61
            write (11,230)
62
            jj=1
         do 12 i=1,3
63
    10
64
            xo(i)=xxo(i)
65
            xs(i)=xxs(i)
66
            do 12 j=1,3
67
            12
               c(i,j)=cc(i,j)
            if(jj.ne.2) go to 15 write(11,240)
68
69
70
            xo(1)=0.0
71
            c(1,1)=0.0
            c(3,1)=1.0
c(1,2)=1.0
72
73
74
            c(3,2)=0.0
75
    15 do 20 i=1,13
76
            do 20 j=1,2
77
         xp(j,i) = 999.
    20
78
79
    C
        read the required input date
80
    C
81
            read(10,260) (xp(1,i),i=1,13)
            read(10,260) (xp(2,i),i=1,13)
82
83
    C
84
            do 30 i=1,13
            xp(1,i)=xp(1,i)*2.54
85
86
            xp(2,i)=xp(2,i)*2.54
87
    30
         continue
            nl=0
88
89
     40 err=0.
            do 50 i=1,9
90
91
            ja(i)=0
92
            do 50 j=1,10
93
    50
         a(i,j)=0
94
            do 100 i=1,13
95
            if (xp(1,i).ge.99..or.xp(2,i).ge.99.) go to 100
96
            do 60 j=1,3
97
            rt(j)=0.
98
            do 60 k=1.3
99
         rt(j)=rt(j)+xt(k,i)*c(j,k)
     60
100
             w(1) = xs(3) / (xs(3) - rt(3) - xo(3))
101
             w(2) = 0.
102
             w(3) = w(1) * (rt(1) + xo(1) - xs(1)) / (xs(3) - rt(3) - xo(3))
103
             w(4) = -w(1) * (rt(3) + xo(3)) / xs(3)
104
             w(5) = 0.
             w(6) = -w(3) * (rt(3) + xo(3)) / xs(3)
105
             w(7) = w(3) * rt(2)
106
             w(8) = w(1) * rt(3) - w(3) * rt(1)
107
108
             w(9) = -w(1) *rt(2)
109
             w(10) = xp(1,i) - xs(1) - w(1) * (rt(1) + xo(1) - xs(1))
             erp=w(10)**2
110
111
             n=0.
          do 80 k=1,10
112
     70
             do 80 j=1,9
113
          a(j,k)=a(j,k)+w(k)*w(j)
114
     80
115
             err=err+w(10)**2
116
             if (n.eq.1) go to 90
             n=1
117
118
             w(2) = w(1)
119
             w(1) = 0.
120
             w(3) = w(2) * (rt(2) + xo(2) - xs(2)) / (xs(3) - rt(3) - xo(3))
```

```
121
             w(5) = w(4)
122
            w(4) = 0.
123
            w(6) = -w(3) * (rt(3) + xo(3)) / xs(3)
            w(7) = w(3) * rt(2) - w(2) * rt(3)
124
125
            w(8) = -w(3) * rt(1)
126
            w(9) = w(2) * rt(1)
127
            w(10) = xp(2,i) - xs(2) - w(2) * (rt(2) + xo(2) - xs(2))
128
            erp=erp+w(10)**2
129
             go to 70
     90 if (nl.eq.20) write (11,270) i,xp(1,i),xp(2,i),erp
130
     100 continue
131
132
     call axeb (a,9,10,ja)
133
     ao=0.
134
     do 110 j=1,3
135
     1 ao=ao+a(j+6,10)**2
136
     1 xo(j)=xo(j)+a(j,10)
137
     1 110 xs(j)=xs(j)+a(j+3,10)
138
     ao=sgrt(ao)
139
     if (ao.lt..25) go to 130
     do 120 j=7,9
140
141
     120 a(j,10)=a(j,10)*.25/ao
142
     130 r=sqrt (1.-a(9,10)**2)
143
     do 140 j=1,3
144
     p=c(1,j)
145
     c(1,j)=p*r-c(2,j)*a(9,10)
146
     140 c(2,j)=p*a(9,10)+c(2,j)*r
147
     r = sqrt(1-a(8,10)**2)
148
     do 150 j=1,3
149
     p=c(1,j)
150
     c(1,j)=p*r+c(3,j)*a(8,10)
151
     150 c(3,j)=r*c(3,j)-p*a(8,10)
152
     r = sqrt(1-a(7,10)**2)
153
     do 160 j=1,3
     p=c(2,j)
154
155
     c(2,j)=p*r-c(3,j)*a(7,10)
160 c(3,j)=p*a(7,10)+c(3,j)*r
156
157
     write (11,280) c,xo,xs,err
158
     nl=nl+1
159
     if (nl.le.20) go to 40
160
     do 170 i=1,3
161
     xsp(i,jj)=xs(i)
     xop(i,jj)=xo(i)
do 170 j=1,3
162
163
     170 cp(i,j,jj)=c(i,j)
164
     do 180 i=1,13
165
166
     xpp(1,i,jj)=xp(1,i)
     180 xpp(2,i,jj) = xp(2,i)
167
168
     jj=jj+1
169
     if (jj.lt.3) go to 10
     write (11,290)
do 210 i=1,13
170
171
172
     ptp=0.
     do 190 j=1,2
173
174
     do 190 k=1,2
175
     ptp=ptp+xpp(j,i,k)
176
     190 pxp(j,k)=xpp(j,i,k)
     if (ptp.gt.99.) go to 210
177
178
     call pxry2 (w(1), pxp, r, w(4))
179
     erp=0.
180
     do 200 j=1,3
181
     200 erp=erp+(w(j)-xt(j,i))**2
     write (11,300) i, (xt(j,i),j=1,3), (w(k),k=1,3), erp
```

```
210 continue
183
184
      C
      230 format ('1 set up parameters - a-p projection', a6)
240 format ('1 set up parameters - lateral projection', a6)
185
186
      250 format (3f10.0)
187
      260 format (13(f7.3,1x))
188
      270 format (5x,i3,2f10.6,f10.7)
189
      280 format (5x,9f10.5)
290 format ('1 back-check multiply acquired cal points'//)
300 format (5x,i3,6f10.4,f10.7)
190
191
192
193
      С
194
NUMBER OF ERRORS = 0 NUMBER OF WARNINGS = 0
```

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```
subroutine pxry2 (x,a,r,xr)
  2
  3
     С
        subroutine pxryz
  4
        This subroutine calculates the best least square coordinates
     С
        in the lab (x(i), i=1,2,3) consistent with the ap & lateral x-ray
 8
        coordinates of all bee bee's and possible right-left ambiguities
 9
        arising from the lateral x-ray view.
10
11
     С
        input consist of:
12
     С
        a(2,2) = the ap,x; ap,y; lat,x; lat,y; measured x-ray coordinates
13
    С
                  of the ith bee bee. i=1,7 for neck monut, i=1,13 for head
14
    C
                  mount. Also known a sp(2,2,13) in subroutine rlswch and
15
                  as spi(4,13) in the main program.
    C
16
    С
17
    С
        xo(3,2) = vectors from lab to x-ray origin (ap:lat) in x-ray coord's
18
19
        xs(3,2) = vector from camera origin to x-ray origin in x-ray coord's
    С
20
21
    С
        c(3,3,2) = transformation matricces from [lab/x-ray]ap:[lab/xray]lat.
22
    C
23
        output consist of:
    С
24
        x(3) = best least squares estimate of bee bee in lab coordinates
    С
25
          = sum of the square of the error between the measured
26
    C
27
             x-ray coordinates and the x-ray coordinates obtained by
    С
28
    С
             projection of the best least squares position of the bee
29
             bee onto both x-ray film planes.
    С
30
    C
31
       r = [ap(x,y)measured-ap(x,y)theory]**2.0 +
    С
32
             [lat(x,y)measured-lat(x,y)theory]
    C
33
    C
34
       xr(2,2) = the x-ray coordinates obtained by projection of the
    С
35
                  calculated position of the bee bee onto the x-ray film
    C
36
    C
                  planes. It is called xtp(4) in the main program.
                  It is used in the neck calculations.
37
    С
38
    C
39
    С
       bench marks of intrest consist of:
40
             = x(1)+det(2)/det(1) the sum of the change in the x
    С
41
    C
                component of the lab coordinates of the bee bee for each
42
                iteration for the best coordinate calculation routine.
    С
43
    С
44
    C
       e = the magnitude of the change squared of x(3) above,
45
            calculated for each iteration of the best coordinates
    С
46
            routine.
    С
47
    C
48
    C
49
          common \frac{b1k2}{xo(3,2)}, xs(3,2), c(3,3,2)
50
          real x(3), a(2,2), xr(2,2), w(4), gm(3,4), det(4), xx(3)
51
          nc=0
52
          do 10 i=1,3
53
    10 x(i)=0.
   20 do 30 i=1,3
55
          do 30 j=1,4
56
    30
        gm(i,j)=0.
          r=0.
57
58
          nc=nc+1
```

```
59
                            do 60 i=1,2
60
                            do 40 j=1,3
61
                            xx(j)=xo(j,i)-xs(j,i)
62
                            do 40 k=1,3
                   xx(j)=xx(j)+c(j,k,i)*x(k)
63
           40
64
                            do 60 j=1,2
65
                            w(4) = a(j,i) + xx(j) / xx(3) * xs(3,i) - xs(j,i)
                            r=r+w(4)**2
66
67
                            do 50 k=1,3
                    w(k) = -(c(j,k,i)-c(3,k,i)*xx(j)/xx(3))*xs(3,i)/xx(3)
68
           50
69
                            do 60 k=1,3
70
                            do 60 1=1.4
                     gm(k,1)=gm(k,1)+w(k)*w(1)
71
           60
                            do 80 i=1,4
72
73
                            \det(i) = gm(1,1) * (gm(2,2) * gm(3,3) - gm(2,3) - gm(3,2)) + gm(1,2) * (gm(2,3) - gm(3,2)) + gm(3,3) - gm(3,2)) + gm(3,3) + gm(3
                      1) *gm(3,1) -gm(2,1) *gm(3,3)) +gm(1,3) *(gm(2,1) *gm(3,2) -gm(3,1) *gm(2,2)
74
75
                      2))
76
                            if (i.eq.4) go to 80
77
                            do 70 k=1,3
78
                            e=gm(k,i)
79
                            gm(k,i)=gm(k,4)
80
           70
                     gm(k,4)=e
81
           80
                     continue
82
                            x(1)=x(1)+det(2)/det(1)
83
                            x(2) = x(2) - det(3) / det(1)
84
                            x(3) = x(3) + det(4) / det(1)
                            e = (det(2) **2 + det(3) **2 + det(4) **2) / det(1) **2
85
86
                            if (e.gt..00001.and.nc.le.10) go to 20
87
                            do 100 i=1,2
                            do 90 j=1,3
88
89
                            xx(j)=xo(j,i)-xs(j,i)
90
          C
91
          С
          c where xo(j,i) = (lab origin - xray origin) in xray coordinates
92
93
                  xs(j,i) = (xray source - xray origin) in xray coordinates
          С
94
           С
95
           С
96
                            do 90 k=1,3
97
           90
                    xx(j)=xx(j)+c(j,k,i)*x(k)
98
           C
99
                  xx(j) = (point - source) in xray coordinates
           C
                              do 100 j=1,2
100
101
102
             100 xr(j,i)=xs(j,i)-xx(j)/xx(3)*xs(3,i)
103
             C
                     -xx(j)/xx(3)*xs(3,i) = (theoretical xray coordinates of a point
104
                    minus source coordinates) in xray system
105
             C
106
                    xr(j,i) = theoretical xray coordinates
107
             С
108
                              return
109
             С
110
                              end
```

NUMBER OF ERRORS = 0 NUMBER OF WARNINGS = 0

NAVAL BIODYNAMICS LABORATORY SOFTWARE DOCUMENTATION

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```
1
           subroutine rlswch (j,k,sp)
 2
    С
 3
    С
        subroutine rlswch
 4
 5
        This subroutine gathers the ap and lat x-ray coordinates of the
    C
 7
        anatomical instrument bee bee's. It then generates additional points
    С
 8
        by making an alternate switch of the possible ambiguities which
    С
        could arise when varying certain bee bee locations on the lateral
 9
10
       x-rays.
    C
11
12
    C
        input and output consist of:
13
    С
        sp(2,2,13) = t the first 28 elements of this array contain the
14
                     measured coordinates of the ap and lat views of the
    С
15
                      the subject's bee bee's, and are passed to this
    С
                     subroutine from the main program. The last 24 elements array are empty and will receive the right-left/left-
16
    С
17
    С
18
    С
                      right switch of coordinates performed by this
19
    С
                     subroutine.
20
    С
21
                     the index of the right side bee bee on the lateral
    С
22
    С
       view as obtained from measurement.
23
24
    C
       k = the index of the right-side bee bee so labeled by
             this subroutine and has identical x-ray coordinates
25
    С
26
             as the measured labeled left side bb. A least square
    C
27
    C
             solution with accompanying error for both labeled bee
             bee's in lab coordinates is determined in subroutine
28
    C
29
    C
             pxry2. If the proper switch is set in subroutine option
30
    С
             the discreptences will be automatically corrected there
31
    С
32
    C
33
           real sp(2,2,13)
34
           1=k+1
35
           do 10 i=1,2
           sp(i,1,k) = sp(i,1,j)
36
37
           sp(i,2,k)=sp(i,2,j+1)
38
           sp(i,1,1) = sp(i,1,j+1)
   10
39
        sp(i,2,1)=sp(i,2,j)
40
           return
41
    С
42
           end
```

NUMBER OF ERRORS = 0 NUMBER OF WARNINGS = 0

APPENDIX B

Listing of "IOUPDATE"

		-
		-
		1

echo Procedure to update xray input file and to execute main program cp \$1 input cp output \$2 cp update \$3 echo Files Saved - Executing Main Xray-Anthropometry Program mxray

APPENDIX C

Listing of "INPUT"

ноогоо 1	0888 110	01 2201	0 0	0 0					
10.386	1.648	1.532	-		999.000	999.000	999.000	9.278	4.890
1.144	4.973	4.818							
-1.914		6.812	7.015	999.000	999.000	999.000	999.000	2.285	2.327
2.359 -	2.526	7.180							
999.000			999.000	2.924	2.415	11.212	11.315	11.119	5.850
286	5.800	5.935							
	999.000		999.000	6.814	-1.942	-2.286	6.697	2.051	1.813
1.548 -	3.216	6.883							
.712	6.362	.994	4.576	2.565	581	5.697			
3.036	3.823	4.461	4.814	5.660	2.627	2.389			
1.778	3.033	7.023	7.421	11.146	10.489	10.542			
2.356	3.491	3.935	4.366	5.072	1.787	1.945			
4.729	4.216	5.040	1.992	7.698					
1.597	-1.608	4.446	4.522	4.175					
6.308	11.900	370	2.328	3.053					
1.045	-1.989	4.237	4.010	3.804					
2.304	1.575	6.920	1.459						
10.223	059	6.750	.369	6.984	.860				

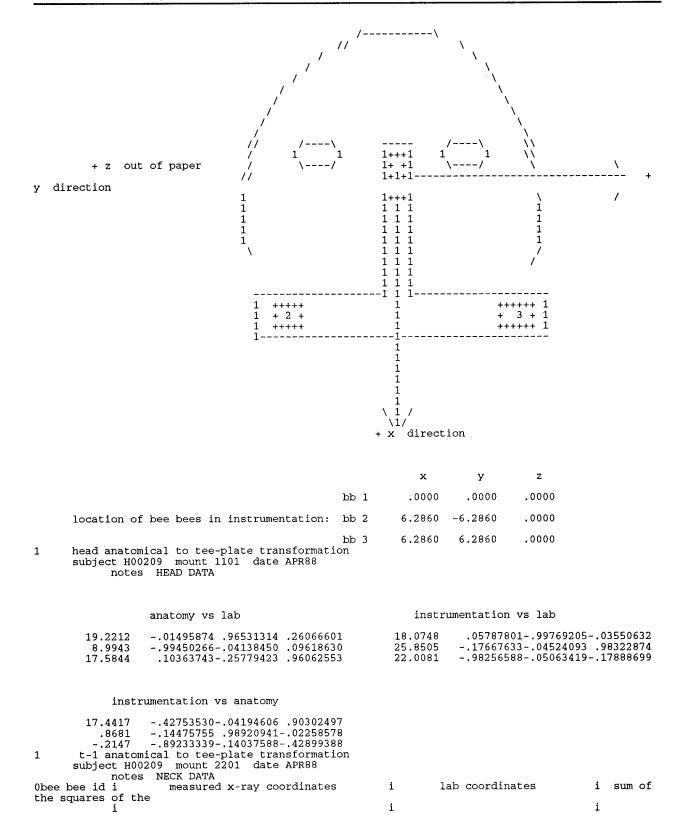
APPENDIX D

Listing of "OUTPUT"

```
set up parameters - a-p projection -.99885 -.01122 -.04663 -.
                                                                              -.01318
                                                                                                      .04199
                                                      -.04255 .99803 -.01318
.70755 173.346161816.69006
                                                                    .99803
                                                                                          .99903
                                           -.04612
                   -9.44438
                               14.62792
                                          29.17912
        31.38578
                                                                                          .99980
                                                                                                      .01082
                                                       -.01310
                                                                   .98943
                                                                              -.01658
          -.98938
                    -.01484
                                -.14458
                                            -.14440
                                          15.29855
                                                      7.45546 185.71568
                                                                              .97425
        30.64409
                   -8.72047
                               19.82321
                                                                              -.01575
                                                       -.01517
                                                                                          .99979
                                                                                                      .01283
                    -.01351
                                -.15944
                                           -.15924
                                                                   .98712
         -.98711
       29.98223
                                                      7.35874 184.20836
                                                                              .66993
                   -8.62734
                               19.63002
                                          11.52374
                                                                                          .99966
                                                                                                      .02084
                                -.15518
                                           -.15487
                                                       -.02303
                                                                   .98767
                                                                              -.01574
          .98781
                    -.01232
                                                               184.01617
                                                                              .01011
        30.08084
                                          12.39414
                                                      5.87360
                   -8.78918
                               19.42020
                                           -.15984
                                                       -.02284
                                                                   .98688
                                                                              -.01583
                                                                                          .99966
                                                                                                      .02058
          .98702
                                -.16015
                    -.01233
                                                      5.90834 184.14708
                                                                               .00986
       29.97732
                   -8.78477
                              19.50641
                                          11.44204
                                                                             -.01581
                                                                                          .99962
                                                                                                      .02259
                                            -.15845
                                                                   .98705
                                -.15878
          .98724
                    -.01202
                                                       -.02481
                                                               184.10239
                                                                              .00981
                                                      5.53493
        30.00607
                                          11.70691
                   -8.82524
                               19.45057
                                                                   .98685
                                                                                          .99962
                                                                                                      .02244
          .98704
                    -.01204
                                -.16004
                                           -.15971
                                                       -.02468
                                                                              -.01583
                                                                             .00979
-.01582
       29.97989
                   -8.82260
                               19.47390
                                          11.46572
                                                      5.55905 184.13451
                                                                                          .99961
                                                                                                      .02293
          .98710
                     -.01196
                                 -.15967
                                            -.15933
                                                       -.02516
                                                                   .98690
                                          11.53778
        29.98773
                   -8.83229
                               19.45997
                                                      5.46947
                                                               184.12390
                                                                              .00979
                                                                              -.01583
                                                                                          .99961
                                                                                                      .02287
                                -.15998
                                            -.15965
                                                       -.02511
                                                                   .98685
         -.98705
                    -.01197
        29.98128
                   -8.83130
                              19.46601
                                          11.47830
                                                      5.47863
                                                               184.13174
                                                                              .00979
                                            -.15955
                                                       -.02522
                                                                   .98687
                                                                              -.01583
                                                                                          .99961
                                                                                                      .02299
          .98706
                    -.01195
                                -.15988
        29.98337
                   -8.83362
                               19.46251
                                          11.49755
                                                      5.45714
                                                               184.12914
                                                                              .00979
                    -.01196
                                -.15996
                                           -.15962
                                                       -.02521
                                                                   .98686
                                                                              -.01583
                                                                                          .99961
                                                                                                      .02297
          .98705
                                          11.48277
       29.98177
                              19.46407
                                                      5.46002 184.13101
                                                                              .00979
                   -8.83331
                                           -.15960
                                                                             -.01583
                                -.15993
                                                       -.02523
                                                                                          .99961
                                                                                                      .02300
                                                                   .98686
          .98706
                    -.01195
                                          11.48775
        29.98231
                                                      5.45484
                                                               184.13026
                                                                               .00979
                               19.46320
                   -8.83387
                                                       -.02523
                                                                             -.01583
                                -.15995
                                           -.15962
                                                                    .98686
                                                                                          .99961
                                                                                                      .02300
           .98705
                    -.01195
                                                      5.45568 184.13075
-.02524 .98686
                                                                             .00979
-.01583
                                          11.48410
        29.98191
                   -8.83378
                              19.46358
                                           -.15961
                                                                    .98686
                                                                                          .99961
                                                                                                      .02300
          .98705
                    -.01195
                                -.15995
                                                               184.13048
                                                                               .00979
                               19.46332
                                          11.48550
                                                      5.45420
        29.98207
                   -8.83394
                                                                    .98686
                                -.15995
                                           -.15961
                                                                              -.01583
                                                                                          .99961
                                                                                                      .02300
          .98705
                    -.01195
                                                       -.02524
                                                      5.45441 184.13077
        29.98194
                   -8.83392
                               19.46347
                                          11.48433
                                                                              .00979
                                           -.15961
                                                                                          .99961
         -.98705
                    -.01195
                                -.15995
                                                       -.02524
                                                                   .98686
                                                                              -.01583
                                                                                                      .02300
                                                                184.13078
        29.98200
                   -8.83394
                              19.46340
                                          11.48492
                                                      5.45422
                                                                               .00979
          -.98705
                    -.01195
                                -.15995
                                           -.15961
                                                       -.02524
                                                                    .98686
                                                                              -.01583
                                                                                          .99961
                                                                                                      .02300
        29.98197
                               19.46343
                                          11.48462
                                                      5.45431 184.13074
                                                                              .00979
                   -8.83393
                                -.15995
                                            -.15961
                                                       -.02524
                                                                    .98686
                                                                              -.01583
                                                                                          .99961
                                                                                                      .02300
         -.98705
                    -.01195
        29.98199
                   -8.83392
                              19.46343
                                          11.48482
                                                      5.45435
                                                                184.13080
                                                                              .00979
                                                                                          .99961
                                -.15995
                                           -.15961
                                                       -.02524
                                                                   .98686
                                                                              -.01583
                                                                                                      .02300
          .98705
                    -.01195
                              19.46336
                                          11.48503
                                                      5.45432 184.13052
                                                                              .00979
        29.98202
                   -8.83393
                                                       -.02524
                                -.15995
                                           -.15961
                                                                   .98686
                                                                              -.01583
                                                                                          .99961
                                                                                                      .02300
         -.98705
                    -.01195
                   -8.83391
                              19.46344
                                          11.48470
                                                      5.45452 184.13078
                                                                               .00979
        29.98198
        1 26.380438 -4.861560
                                  .0008375
           4.185920 -4.937760
3.891280 17.302479
                                  .0010381
                                  .0026324
        4 26.093418 17.818100
9 23.566120 5.803900
                                  .0012070
                                  .0008343
      10 12.420600
11 2.905760
                     5.910580
5.991860
                                  .0001535
                                  .0020173
      12 12.631420 -6.416040
13 12.237720 18.237200
                                  .0005440
                                  .0005259
                                                      -.02524
                                           -.15961
                                                                   .98686
                                                                             -.01583
                                                                                          .99961
                                                                                                      .02300
                                ~.15995
           .98705
                    -.01195
                                                      5.45443 184.13060
        29.98200
                  -8.83391
                              19.46340
                                          11.48492
                                                                               .00979
      set up parameters - .04389 - .00293
                             lateral projection
1
                                                                  -.04393
                                                                                          .99988
                                                                                                      .00227
                                                       -.01517
                                 .99903
                                             .99892
                                                     16.28766 150.192081487.97229
         3.16778
                   -8.97930
                               15.70602
                                          44.45662
         -.08163
                    -.04970
                                 .99542
                                            .99648
                                                       -.02306
                                                                    .08056
                                                                               .01895
                                                                                          .99850
                                                                                                      .05141
                                                                            45.38939
         2.51471
                               13.89865
                                          23.52338
                                                      8.10413 149.23682
                   -8.81139
          .17244
                    -.05655
                                 .98340
                                             .98496
                                                       -.02059
                                                                    .17153
                                                                               .01055
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                                           9.24914
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                                                       -.01278
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          .17404
                                                     14.33915 139.10625
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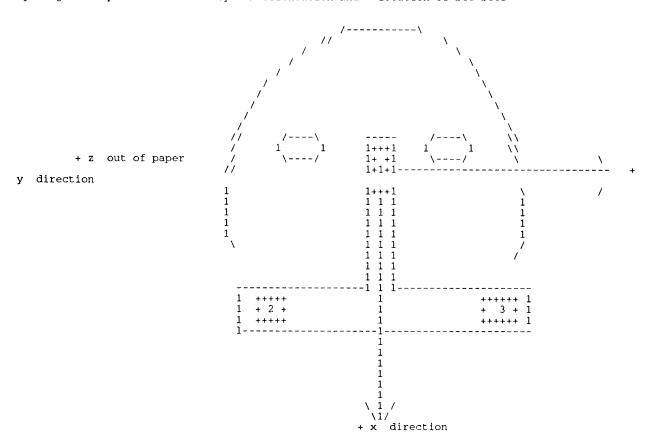
NAVAL BIODYNAMICS LABORATORY SOFTWARE DOCUMENTATION

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                                                                             .03517
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        7 28.478479 -5.806440
8 28.740099 17.010380
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                                 .0026793
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0 14.858999 4.605020
                                 .0089725
       10 14.858999
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     back-check multiply acquired cal points
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                       25.4000
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                                              5.0860
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            15,2400
                       15.2400
                                  25.4000
                                             15.2366
                                                        15.2699
                                                                   25.4122
                                                                             .0010533
      head anatomical to tee-plate transformation
      subject H00209 mount 1101 date APR88
                                                  notes HEAD DATA
Obee bee id i
                       measured x-ray coordinates
                                                                     lab coordinates
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the squares of the
             i
                                                                                                i
difference between the
                                                            i
                                                                                                i
measured and best estimate
            i
                                                            i
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x-ray coordinates
            i
                                                                            y
9.0287
8.9599
                         y
7.7114
  1 r.audit
                                                                25.4972
12.9452
                1.8085
                                        4.5161
                                                    5.9842
                                                                                     16.8190
                                                                                                     .0031
  2 l.audit
               16.1595
                           9.7104
                                        7.7038
                                                    8.8671
                                                                                     18.3497
                                                                                                     .0029
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                2.5248
                          11.3309
                                       17.8384
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                                                                22.8189
                                                                           18.4356
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  4 1.orbit
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                          12.2276
                                       18.8493
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  5 c.t-plt
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                                                                                                     .0007
  6 r.t-plt
               -1.4757
                           6.6726
                                       26.6421
                                                   4.5390
                                                               24.6725
                                                                          25.0227
                                                                                     16.1485
                                                                                                     .0015
  7 1.t-plt
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                                                                12,2026
                                                                          24.4568
                                                                                     15.5134
                                                                                                      .0011
               right/left switch follow below 1.8085 7.7114 7.7038
0 8 r.audit
                                                   8.8671
                                                                24.9421
                                                                          11.2660
                                                                                      18.0525
                                                                                                    3,7105
  9 l.audit
               16.1595
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                                                   5.9842
                                                                13.3660
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 10 r.orbit
                2.5248
                          11.3309
                                       18.8493
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                                                                                                     .6052
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               11.6230
                          12.2276
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13 l.t-plt
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                                                               24.6381
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                           6.0681
                                       26.6421
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  option 1 vs 8 not indicated option 3 vs 10 not indicated option 6 vs 12 not indicated
1plexiglass t-plate coordinate system-orientation and location of bee bees
```



NAVAL BIODYNAMICS LABORATORY SOFTWARE DOCUMENTATION

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difference between the
                                                                i
                                                                                                     i
measured and best estimate
                                                               i
                                                                                                        of
             i
                       ap
                                                lat
                                                                                                     i
x-ray coordinates
             i
               x
12.0117
10.7086
                           4.0564
-4.0843
                                         x
16.0223
                                                                   x
15.4639
                                                                                          z
13.7306
7.9246
             i
                                                      2.6543
0 1 p-spine
                                                                               16.1980
                                                                                                           .0004
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                                                                                          19.8886
                                                                                                           .0269
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                           10.6045
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                                                      9.6622
                                                                   10.0794
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                right/left switch follow below 5.0597 11.4859 7.7546
                          11.4859
10.6045
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 7 l.t-plt 19.5529 10.6045 option 4 vs 6 not indicated
                                          5.9131
                                                     10.1854
                                                                   10.2519
                                                                               6.8995
                                                                                          19.1873
                                                                                                           .0556
1plexiglass t-plate coordinate system-orientation and
                                                                location of bee bees
```



				x	У	z
			bb 1	.0000	.0000	.0000
	location of bee bee	es in instrument	tation: bb 2	6.2860	-6.2860	.0000
			bb 3	6.2860	6.2860	.0000
0	articular facets	5.8522 4.00	05 17.5768	3.7059		
0	lateral projection	25.96641	17.4422	1.5608		
	14.9090	24.0173	11.6953			
	15.4044	17.3306	12.8952			
1	t-1 anatomical to subject H00209 mov notes NECK I					

anatomy vs lab

instrumentation vs lab

21.02.0	07271960 .9816716917616072	16.7738	074669449941154107847808
	996005240806576603831476	2.6720	.9948193407970386 .06310345
	05182123 .17267077 .98361552	19.8644	0689871207335965 .99491668

instrumentation vs anatomy

-22.5287	.99416876	.00697174-	10761147
4487	00322542	.99938363	.03495481
4.2529	.10778888-	.03440393	.99357843

APPENDIX E

Listing of "UPDATE"

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H00209 2201 APR88		DATA	0	0	Ü	0
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